IN THE CLAIMS:

Please cancel claim 7 and amend the claims as follows:

1. (Cancelled)

2. (Currently Amended) An apparatus for handling a tubular, the apparatus being coupled to a trough for transporting the tubular to a wellbore, comprising:

at least two arms ~~one arm, the arm~~ ~~operatively~~ coupled to a body, the body coupled to the trough, wherein the trough is configured to carry the tubular from a substantially horizontal position to the wellbore, wherein each of the at least [[one]] two arms are ~~arm is~~ movable in two or more planes relative to the body, wherein the body is movably coupled to the trough and the tubular is retained between the body and the at least two arms ~~one arm~~, and

wherein the at least two arms ~~one arm~~ is actuatable to limit movement of the tubular relative to the trough.

3-4. (Cancelled)

5. (Currently Amended) The apparatus of claim 2, wherein ~~the arm~~ at least one of the at least two arms include ~~includes~~ a stop member for contacting the tubular.

6. (Currently Amended) The apparatus of claim 5, wherein the ~~apparatus comprises two~~ at least two arms and the stop member [[is]] are adapted to retain the tubular between the two arms.

7. (Cancelled)

8. (Currently Amended) The apparatus of claim 7, wherein the at least two arms are actuatable between an open position wherein the arms do not contact the tubular and a closed position wherein the arms contact the tubular.

9. (Previously Presented) The apparatus of claim 8, wherein a stop member is adapted to retain the tubular between the at least two arms when the at least two arms are in the closed position.

10. (Previously Presented) The apparatus of claim 9, wherein each arm includes the stop member.

11. (Cancelled)

12. (Currently Amended) The apparatus of claim 35, wherein the at least two arms are adapted to control the movement of tubular when the arms are in the raised position.

13-32. (Cancelled)

33. (Currently Amended) The apparatus of claim 8, further comprising a first actuator couplable to the at least two arms configured to move the two arms between the open and the closed position.

34. (Currently Amended) The apparatus of claim 33, further comprising a second actuator couplable to the at least two arms and the body and configured to move the [[two]] arms between a raised position and a lowered position.

35. (Previously Presented) The apparatus of claim 34, wherein in the lowered position the arms are substantially parallel with the trough and the raised position the arms are substantially perpendicular to the trough.

36. (Currently Amended) The apparatus of claim 34, further comprising a third actuator coupleable to the body and the trough and configured to move the body relative to the trough.

37. (Currently Amended) The apparatus of claim 36, wherein the body is ~~movable~~ pivotable about a connection to the trough and is configured move the tubular in a horizontal plane in order to align the tubular with the wellbore.

38. (Previously Presented) The apparatus of claim 2, wherein the through is adapted to cradle the tubular longitudinally while in a horizontal position and guide an end of the tubular while a first end of the tubular is lifted.

39. (Previously Presented) The apparatus of claim 38, wherein the body is coupled to an end of the through and adapted to control the movement of the tubular as a second end of the tubular reaches the end of the trough.

40. (Currently Amended) A method of positioning a tubular above a wellbore, the tubular having a first end and a second end, the method comprising:

providing a carriage having a wellbore end and a distal end;

providing a tubular handling apparatus coupled to the wellbore end of the carriage, the tubular handling apparatus having a body and one or more arms;

transporting the tubular in the carriage from a substantially horizontal position to a position wherein the wellbore end of the carriage is adjacent the wellbore;

lifting the first end of the tubular off of the carriage and above the wellbore;

engaging the second end of the tubular with the one or more arms;

actuating the one or more arms to pivot the arms in a first plane relative to the body while removing the second end of the tubular from the carriage;

actuating the body to pivot the body about an axis which is at an angle relative to a longitudinal axis of the carriage ~~relative to the carriage~~ thereby pivoting ~~to align~~ the second end of the tubular in a horizontal plane and aligning the tubular with the wellbore; and

actuating the one or more arms to pivot the arms in a second plane relative to the body to release the tubular when the second end is above the wellbore.

41. (Previously Presented) The method of claim 40, wherein the carriage is configured to receive a portion of the tubular along a longitudinal axis of the tubular.

42. (Previously Presented) The method of claim 40, further comprising running the second end of the tubular along the carriage while lifting the first end of the tubular until the second end of the tubular engages the one or more arms.

43. (Previously Presented) The method of claim 40, wherein the first plane is a substantially vertical plane.

44. (Currently Amended) The method of claim 43, ~~where~~ wherein the first plane is substantially parallel with the carriage.

45. (Previously Presented) The method of claim 43, wherein the second plane is substantially horizontal.

46. (Previously Presented) The method of claim 45, wherein the arms pivot away from each other in the second plane.

Please add the following new claims:

47. (New) The apparatus of claim 36, wherein the third actuator is configured to pivot the body about an axis which is substantially normal to a longitudinal axis of the trough, thereby pivoting the tubular in a horizontal plane in order to align the tubular with the wellbore.

48. (New) The method of claim 40, further comprising guiding the tubular between a stop member of the one or more arms and the body while lowering the tubular toward the wellbore.

49. (New) The method of claim 40, further comprising actuating the body in order to extend the distance between the one or more arms and the carriage thereby moving the tubular toward the wellbore.

50. (New) An apparatus for handling a tubular, the apparatus being coupled to a trough for transporting the tubular to a wellbore, comprising:

a body coupled to the trough;

at least one arm coupled to the body, wherein the trough is configured to carry the tubular from a substantially horizontal position to the wellbore and the at least one arm and the body are configured to control the movement of the tubular as the tubular is removed from trough;

a first actuator operatively coupled to the body and the trough and configured to pivotably move the body and thereby the at least one arm in a first plane relative to the trough;

a second actuator operatively coupled to the at least one arm and the body and configured to pivotably move the at least one arm in a second plane relative to the body and the trough between a travel position in which the at least one arm is substantially parallel with the trough to a contact position in which the at lease one arm is at an angle relative to the trough; and

a third actuator configured to pivot the at least one arm relative to the body in a third plane in order to engage and disengage the tubular.

51. (New) The apparatus of claim 50, wherein the at least one arm comprises two arms.

52. (New) The apparatus of claim 51, wherein the first actuator comprises two piston and cylinder assemblies.